AIAA 80-1334R

# **Buoyancy Effects in Turbulent Mixing: Sampling Turbulence in the Stratified Ocean**

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Stable stratification in the ocean and atmosphere tends to suppress turbulence, mixing, and vertical diffusion. Active turbulence is often confined to isolated patches which occur intermittently in time, decay rapidly, and occupy a small volume fraction of most layers. Estimates of mean dissipation rates  $\epsilon$  and  $\chi$  of turbulent velocity and temperature from short vertical or short horizontal records in a layer may underestimate the space-time mean values by orders of magnitude under common oceanic conditions due to undersampling errors. If  $\chi$  is lognormal the short record sample values will probably be less than the space average for the layer by a factor of exp  $(3\sigma^2/2)$ , the ratio of mean/mode for a log-normal distribution, where  $\sigma^2$  is the variance of  $\ln \chi$ . Variation of  $\epsilon$ and  $\chi$  with depth from dropsondes actually may be a better indication of the vertical variation of  $\sigma_{\ell_n(\epsilon,\chi)}^2$  than variation of  $(\epsilon, \chi)_{\text{mean}}$ ; for example, dropsonde values of  $\epsilon$  and  $\chi$  in the strongly stratified core region of equatorial undercurrents (probably large  $\sigma$ ) are much smaller than in the sheared layers above and below (probably smaller  $\sigma$ ). Towed body  $\epsilon$  and  $\chi$  values in the core are larger than either the dropsonde core or shearlayer values, possibly because tow bodies collect more data and include more of the active patches which dominate the average for a layer. Space averages may underestimate space-time averages if the space average turbulence is intermittent in time. A tentative correction procedure is described based on information about previous active turbulence preserved by fossil turbulence microstructure. Most oceanic temperature microstructure appears to be fossil turbulence, suggesting such a correction procedure may permit inferences about the turbulence processes occurring a few hours or even days prior to the actual microstructure measurements

#### I. Introduction

THE purpose of the present paper is to describe some effects of stable stratification on turbulence and turbulent mixing, particularly in the ocean and atmosphere, and to discuss some resulting problems in sampling turbulence in the ocean. Fluids in nature typically form stratified layers in a gravity field. Buoyancy forces develop which prevent and suppress turbulence. Consequently, even though a complex field of internal waves and shears may exist in a stratified fluid, turbulence may be confined to scattered intermittent patches. Vertical diffusion and mixing may be inhibited strongly. Measurement techniques must take into account the patchiness and intermittency of stratified turbulence to be reliable.

Vertical diffusion in the atmosphere, oceans, and lakes by nonturbulent molecular processes is very slow. Though the turbulence may be constrained by buoyancy to a small volume fraction of space time it may still be the dominant diffusion process. Smog accumulation over cities and eutrophication of lakes and seas are examples of the adverse affects of turbulence inhibited by buoyancy. Smoke stacks and oceanic sewer outfalls take advantage of the weak diffusivity of stratified flows to prevent diffusion of smoke to the ground or sewage to the sea surface by discharging into stratified layers.

Theoretical and experimental studies of stratified turbulence and turbulent mixing are in an early stage of development, as discussed in Turner's book 1 on the subject. Radar and sonar backscatter observations show a patchy layered pattern of presumably turbulent<sup>2</sup> refractive index fluctuations related to internal wave motions in the stratified atmosphere and ocean, respectively, but few direct measurements of the local velocity and density structure have been available for detailed analysis. Laboratory measurements have been useful, but have uncertain applicability to natural conditions because of the comparatively limited range of length and time scales.

Atmospheric turbulence studies generally have been in the surface boundary layer within neutrally or unstably stratified flows. Aircraft studies have shown the existence of "clear air turbulence" patches in the stratified layers, but because of the high speed of the platform and limited response of the sensors little has been done to document less active regions.

Studies of small-scale velocity and temperature fluctuations in the ocean have been carried out for nearly twenty years from towed bodies and submarines.<sup>3</sup> However, oceanic turbulence and mixing signals are extremely weak compared to those produced by laboratory and atmospheric flows. Frequency response and spatial resolution requirements are high. Consequently, most towed body and submersible measurements of oceanic turbulence have been contaminated to some extent by platform noise. Advances in instrumentation and techniques to decouple the towed body from ship motions have improved signal to noise ratios. Some recent results will be discussed in later sections of this paper.

To avoid platform noise, several vertically profiling instruments have been developed either with internal recording for free-falling devices or with thin wires for data transmission and instrument retrieval. These vertical profilers, or "dropsondes," have been deployed in a wide variety of oceanic regions to depths of a few kilometers. Signal to noise ratios are excellent below surface wave depths, and because such instruments descend slowly, 10-50 cm/s, frequency response requirements are not severe. Unfortunately, a single vertical cut may not provide enough data to characterize the turbulence and mixing processes of a stably stratified oceanic layer because of the patchiness and intermittency of the processes.

Presented as Paper 80-1334 at the AIAA 13th Fluid and Plasma Dynamics Conference, Snowmass, Colo., July 14-16, 1980; submitted Sept. 16, 1980; revision received April 21, 1981. Copyright © American Institute of Aeronautics and Astronautics, Inc., 1980. All rights reserved.

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Temperature fluctuations are generally easier to measure than velocity fluctuations from either towed bodies or dropsondes. Consequently, most reported oceanic microstructure signals are temperature. Schedvin6 has examined temperature signals from various stratified regions below a wind mixed layer using a profiling towed body. The microstructure was found to be quite inhomogeneous in the horizontal direction, with variation of the thermal dissipation rate by several orders of magnitude. Spectra at different angles of attack taken from statistically homogeneous regions showed that most of the microstructure was vertically stratified at the largest scales and approached isotropy only at small scales, suggesting that the turbulence that generated the microstructure had been damped out or strongly affected by buoyancy. Such temperature microstructure remnants of previous active turbulence in nonturbulent fluid are termed "fossil temperature turbulence." Properties of fossil temperature, salinity, and vorticity turbulence have been discussed by Gibson.<sup>7</sup> Using a turbulence activity parameter  $A_T$  (Sec. IV) criterion it was found that the towed body temperature microstructure measurements of Schedvin<sup>6</sup> and all of the published temperature microstructure data from dropsondes indicates a state of complete or partial fossilization. Thus it appears that neither the towed body nor dropsonde records have been of adequate length or time duration to observe the rare turbulence events that produce the observed microstructure.

For nonstratified flows such as the atmospheric boundary layer near the surface, it has been possible to develop and test equations relating the viscous and thermal dissipation rates to the mean momentum and heat fluxes. Similar "dissipation flux" relations have been proposed for stratified media by Osborn and Cox. However, measurement of average dissipation rates are complicated by buoyancy effects such as fossilization and the intermittency in time and patchiness in space of the turbulence. In the following sections, the magnitudes and possible means of accounting for such buoyancy effects will be discussed.

# II. Dissipation Flux Estimates

In steady, homogeneous, nonstratified turbulent shear flows the production of turbulent kinetic energy and scalar variance are balanced by the viscous and diffusive dissipation rates  $\epsilon$  and  $\chi$ , respectively, where

$$\epsilon = 2\nu e_{ij}^{2}; \quad e_{ij} = \frac{1}{2} \left( \frac{\partial u_{i}}{\partial x_{j}} + \frac{\partial u_{j}}{\partial x_{i}} \right); \quad i, j = 1, 2, 3$$

$$\chi = 2D \left( \frac{\partial \theta}{\partial x_{i}} \right)^{2}$$

and D,  $\nu$  are molecular diffusivities of  $\theta$  and momentum.

The production rate of turbulent kinetic energy per unit mass is  $-u'_1u'_3(\partial u_1/\partial x_3)$  and the production rate of  $\theta$  variance is  $-2u'_3\theta(\partial\theta/\partial x_3)$ , where the turbulent momentum and  $\theta$  fluxes and gravity are in the  $x_3$  direction, and the mean flow is in the  $x_1$  direction. Primes indicate fluctuations about mean values and overbars indicate averages (see Tennekes and Lumley  $\theta$  for details, pp. 63 and 65).

Since the mean shear and mean scalar gradients are usually easy to measure, estimates of the fluxes can be made from measurements of  $\epsilon$  and  $\chi$ . Comparisons of such dissipation fluxes  $\epsilon/(\partial \bar{u}_1/\partial x_3)$  and  $\chi/2(\partial \bar{\theta}/\partial x_3)$  with direct measurements of  $-u_1'u_3'$  and  $-u_3'\bar{\theta}'$  in careful atmospheric boundary-layer experiments have been quite successful. <sup>10</sup>

Osborn and Cox<sup>8</sup> have proposed that  $-\theta u_3'$  may equal  $\chi/2(\partial\bar{\theta}/\partial x_3)$  in the ocean. Osborn<sup>11</sup> has estimated temperature fluxes in the Atlantic Equatorial Undercurrent and other ocean regions from  $\chi$  and  $\partial\bar{\theta}/\partial x_3$  measurements from dropsondes. <sup>12</sup>

By assuming that the flux Richardson number  $R_f = \dot{P}E/\epsilon$  is constant and that  $-(\dot{P}E+\epsilon)$  equals the turbulent kinetic energy production rate  $\dot{K}E$ , Osborn<sup>11</sup> also estimated vertical density flux rates, where  $\dot{P}E = \overline{gu_3'\rho'}/\rho$  is the potential energy production rate per unit mass due to turbulent mixing, g the acceleration of gravity, and  $\rho$  the density.

Gregg <sup>13,14</sup> has used dropsonde  $\chi$  measurements to estimate eddy diffusivity coefficients  $K_T$  for temperature in a wide variety of ocean regions, where  $K_T = \chi/2(\partial \bar{T}/\partial x_3)^2$ . Generally such dissipation eddy diffusivities from dropsonde dissipation rate measurements are much smaller than bulk  $K_T$  estimates from mean temperature, salinity, or oxygen content measurements. In a steady flow with current  $\nu_x$  the bulk vertical eddy diffusivity is often estimated as  $\nu_x(\partial s/\partial x)/(\partial^2 s/\partial z^2)$ , where s is a conserved scalar fluid property. Sverdrup et al. <sup>15</sup> state (p. 483) that most bulk

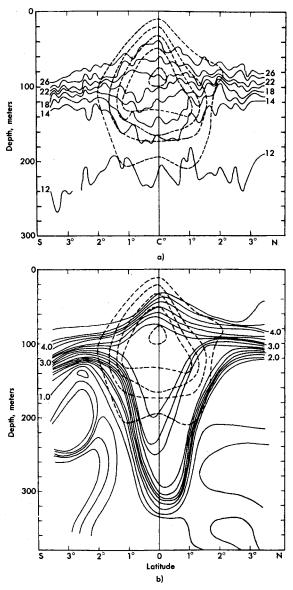


Fig. 1 Velocity cross section (dashed lines) superimposed on a) temperature and b) oxygen sections through the Cromwell Current at longitude  $140^{\circ}$  W.  $^{30}$  The broadening of isotherms and iso-oxygen surfaces near the core of the undercurrent at 100 m on the equator suggests strong turbulent mixing. Towed bodies at the core give  $\epsilon \approx 0.1$  cm  $^2/s^3$  and  $\chi \approx 10^{-4}\,^{\circ}$  C  $^2/s$  (strong turbulence and turbulent mixing) but dropsondes give  $\epsilon \sim 10^{-5}$  cm  $^2/s^3$  and  $\chi \sim 10^{-8}\,^{\circ}$  C  $^2/s$  (laminar flow and mixing only by molecular diffusion). The discrepancy may be due to large sampling errors in the dropsonde estimates, which are based on short records of the extremely patchy and intermittent turbulence process.

Table 1	Hydrodynamic states in Atlantic Equatorial Undercurrent
	implied by dropsonde $\epsilon$ measurements of Osborn $^{11}$

Layer	$\epsilon$ , cm <sup>2</sup> /s <sup>3</sup>	N, rad/s	$L_R$ , cm	$L_K$ , cm	$L_R/10L_K$	Hydrodynamic state (implied)
High shear above core, 20-60 m	3×10 <sup>-3</sup>	1.5×10 <sup>-2</sup>	30	0.15	20	Weakly turbulent
Core region, 60-110 m	$3 \times 10^{-5}$	$2.4 \times 10^{-2}$	1.5	0.49	0.31	Laminar
High shear below core, 110-148 m	$5 \times 10^{-4}$	$1.0 \times 10^{-2}$	22	0.24	9.1	Weakly turbulent

oceanic  $K_T$  values are in the range 3-90 cm<sup>2</sup>/s. However, Gregg reports  $K_T$  values in the North Pacific Gyre of only 0.1 cm<sup>2</sup>/s. Osborn<sup>11</sup> reports even smaller  $K_T$  values in the core (layer of maximum speed) of the Atlantic Equatorial Undercurrent, ranging from 0.006 to 0.04 cm<sup>2</sup>/s compared to a value of 25 cm<sup>2</sup>/s estimated by Williams and Gibson<sup>16</sup> in the core of the Pacific Equatorial Undercurrent from measurements using a towed body. Measurement discrepancies of 3-4 orders of magnitude are remarkable, even in the sometimes uncertain field of experimental turbulence, and require explanation.

Figure 1 shows the distribution of temperature, oxygen, and velocity as a function of depth in a north south section of the Pacific Equatorial Undercurrent, or Cromwell Current, measured by Knauss and discussed by von Arx<sup>17</sup> (p. 176). A huge volume of water, comparable to the Gulf Stream, flows from west to east beneath east to west surface currents, with maximum relative velocity of about 3 knots at a depth of about 100 m. The Atlantic Equatorial Undercurrent is similar in size, speed, direction, and depth. The cause of these currents is unknown.

A very striking feature of the temperature distribution at the equator is the broadening of the thermocline about the undercurrent. The undercurrent is shown by dashed lines of constant speed. Similarly the oxygen concentration spreads about the current, with concentrations found at 150-m depth 2-deg north and south of the equator penetrating over 300-m depth at 0-deg latitude. According to Osborn,  $^{11}$   $K_T$  and  $K\rho$ values in the high shear layers above the core of the undercurrent are in the range 1-4 cm<sup>2</sup>/s, but in the 20-40-m thick core region they fall to only 0.006-0.04 cm<sup>2</sup>/s. In the sheared zone below the core they abruptly rise to the range 0.2-3 cm<sup>2</sup>/s. This pattern of  $K_T$  values seems inconsistent with the observed oxygen and temperature distributions. If heat and oxygen are diffusing down through the current, such large gradients in diffusivity should be accompanied by large gradients in the diffused quantities, yet no such strong gradients in either temperature or oxygen appear in the distributions shown in Fig. 1. Either a system of lateral advection or sources and sinks must be postulated, or else the eddy diffusivities estimated from the dropsonde dissipation rates must not be representative of the actual average values for the layers.

Since a dropsonde makes only a single vertical cut through each stratified layer, it is necessary to consider the possibility that the average dissipation rate for the sample is not representative of the average value of dissipation rate in the layer. This is a familiar problem in atmospheric boundary-layer turbulence dissipation measurements, where it is usually necessary to average several kilometers of air to obtain convergence of  $\epsilon$  and  $\chi$  averages.  $\epsilon$  and  $\chi$  are quite intermittent because of the high Reynolds number of the atmospheric flow.

The thickness of statistically independent stratified layers should be the maximum scale of vertical turbulence  $L_R = (\epsilon/N^3)^{\frac{1}{2}}$ , or Ozmidov length, where N is the buoyancy frequency  $[(g/\bar{\rho})(\partial \bar{\rho}/\partial z)]^{\frac{1}{2}}$ . Osborn's  $\epsilon$  values from the undercurrent core are about  $3 \times 10^{-5}$  cm<sup>2</sup>/s<sup>3</sup> with N values of

about  $2.4 \times 10^{-2}$  rad/s, so Ozmidov lengths are only about 1.4 cm. Even in the sheared layers above the core where  $\epsilon = 3 \times 10^{-3}$  cm<sup>2</sup>/s<sup>3</sup>,  $K\rho = 4$  cm<sup>2</sup>/s, and  $N = 1.5 \times 10^{-2}$  rad/s,  $L_R$  values are only 30 cm. Below the core, where  $\epsilon \sim 5 \times 10^{-4}$  cm<sup>2</sup>/s<sup>3</sup>,  $N = 10^{-2}$  rad/s and  $K\rho \sim 1$  cm<sup>2</sup>/s,  $L_R$  is only 23 cm.

 $L_R$  values are only 30 cm. Below the core, where  $\epsilon \sim 3 \times 10$  cm<sup>2</sup>/s<sup>3</sup>,  $N = 10^{-2}$  rad/s and  $K\rho \sim 1$  cm<sup>2</sup>/s,  $L_R$  is only 23 cm. In order for the turbulence to exist, <sup>7,28</sup>  $L_R$  must be larger than the viscous scale  $\approx 10L_K = 10(\nu^3/\epsilon)^{1/4}$ . This conclusion follows from  $(L_R)_t \sim (L_K)_t$ ,  $R_i = N^2/(\partial u/\partial z)^2 = 1/4$ , and  $(\partial u/\partial z)^2 \approx 2\epsilon_t/15\nu$  at the transition to turbulence in a stratified fluid, which gives  $\epsilon_t = 30\nu N^2$ . Recent measurements in a stratified turbulent grid flow in a water tunnel by Stillinger and Helland<sup>29</sup> give  $\epsilon_t = 23\nu N^2$ . However,  $10L_K$  is 9 cm in the core and 1.5 and 2.4 cm in the shear layer above and below the core, respectively. Therefore, using the dropsonde measurements of  $\epsilon$  as estimates of the average for these regions, the undercurrent core region should be completely nonturbulent and the sheared layers only weakly turbulent. Table 1 summarizes the parameters and implied hydrodynamic states for the three regions of the Atlantic Equatorial Undercurrent discussed by Osborn. <sup>11</sup>

Diffusion of oxygen by molecular processes through a 20-m thick nonturbulent layer is astronomically slow. The diffusion time constant  $L^2/D$  for such a layer is of order 1000 yr. Extraordinarily high levels of organic productivity characteristic of equatorial regions requires rapid vertical exchange of oxygen and nutrients. It has usually been assumed that the high equatorial productivity is a result of strong turbulent mixing produced by the undercurrent, contrary to the dropsonde evidence that the core of the current is non-turbulent and the shear layers only weakly turbulent.

If a stratified layer is not horizontally homogeneous a single vertical sample  $\bar{\epsilon}(L_R,z)$  will probably not equal the actual average  $\bar{\epsilon}(L \to \infty, z)$ , where L is the length scale of the averaging volume. If the layer is quite patchy, the random variable  $\bar{\epsilon}(L_R,z)$  may have a wide probability density function with mode very much smaller than the mean. If the dissipation rates in all layers of the core region were identically distributed, then a vertical profile might be considered a collection of a large number of independent samples of the very thin, weakly diffusive layers in the 20-40-m thick core, so the vertical averages of these samples might be representative of the horizontal average of each layer. However, if the actual average values are large and variable, and if the patchiness varies with depth, the vertical average is of little value: the average of nonrepresentative samples does not become representative.

Measurements of  $\epsilon$  in the core of the Atlantic Equatorial Undercurrent by Belyaev et al. <sup>18,19</sup> using a towed body indicate extreme patchiness and mean values much larger than the dropsonde values. Local values greater than 1 cm<sup>2</sup>/s<sup>3</sup> are reported with mean values of 0.1 cm<sup>2</sup>/s<sup>3</sup>.  $\epsilon$  and  $\chi$  values from other areas were generally much larger than those inferred from dropsondes.

Similarly,  $\chi$  values measured by Williams and Gibson<sup>16</sup> from a towed body in the core regions of the Pacific Equatorial Undercurrent are much larger than dropsonde values. Gregg<sup>13</sup> reports  $\chi$  values of  $10^{-8}$ °C<sup>2</sup>/s compared to  $10^{-4}$ °C<sup>2</sup>/s for the tow-body measurements from the same

depth range. The Osborn and Bilodeau 12 values of  $\chi$  from the core of the Atlantic Equatorial Undercurrent overlap Gregg's with  $\chi$  in the range  $10^{-8}$ - $10^{-6}$ °C<sup>2</sup>/s. As Gregg<sup>13</sup> points out, the towed-body measurements are much noisier than those from dropsondes, which might account for the fact that towed-body estimates of  $\epsilon$  and  $\chi$  are consistently larger. However, Gregg's suggestion 13 that the towed-body temperature signal could be vertical vibrations of the sensors in a vertical temperature gradient was shown to be unlikely by Schedvin. 6 Schedvin used accelerometers to measure vibrations of the same towed body used by Williams and Gibson<sup>16</sup> in a comparable vertical temperature gradient, and found that this sort of vibrational temperature gradient noise was  $10^{-7}$  less than the measured signal (pp. 134 and 135)<sup>6</sup> at the dissipation scales. Another possibility is that the dropsondes may undersample  $\epsilon$  and  $\chi$  when the turbulence is very patchy and these quantities range over 6 orders of magnitude. Gregg 13 observed well-mixed patches in the core region of the Pacific Equatorial Undercurrent of vertical thickness about 2 m. If these patches were caused by turbulence, the originally active turbulence  $\epsilon_0$  values should be about 1.7 cm<sup>2</sup>/s<sup>3</sup>, close to the extreme Belyaev et al. <sup>18,19</sup> values, and original  $\chi_0$  values should be about  $1.1 \times 10^{-3}$  °C<sup>2</sup>/s (see Sec. IV).

If the turbulence is intermittent as well as patchy, even a very large number of samples in a layer from either a tow body or dropsonde may underestimate the averages unless they are carried out over a long time period. In Sec. IV the possibility of using fossil turbulence properties to compensate for intermittency in time is discussed.

# III. Probability Laws for Dissipation Rates

Average  $\epsilon$  and  $\chi$  values are important parameters of any flow or mixing process. As indicated in the last section, the variability in time and space of  $\epsilon$  and  $\chi$  may affect the sampling procedures required to estimate true mean values. Furthermore, the probability laws describing the variability of  $\epsilon$  and  $\chi$  are determined by the physical processes and may provide important information about these processes. It is as important to know whether  $\epsilon$  and  $\chi$  are homogeneous and stationary or patchy and intermittent as it is to know their averages. If  $\epsilon$  and  $\chi$  are patchy and intermittent, it is important to determine the "distances between patches" and the "times between bursts" (to use a bimodal description of the probability laws).

Dissipation rates in high Reynolds number nonstratified flows become increasingly intermittent and patchy as the Reynolds number increases. Kolmogoroff<sup>20</sup> proposed a refinement to his earlier universal similarity hypotheses to take this into account, assuming that the logarithm of  $\epsilon$  should be normally distributed with variance increasing with Reynolds number. Both  $\epsilon$  and  $\chi$  have been shown to have lognormal tendencies in high Reynolds number nonstratified flows. <sup>21</sup>

In stratified flows the physical arguments in support of log normality for  $\epsilon$  and  $\chi$  are complicated by the existence of several mechanisms besides the turbulence cascade that can produce dissipation. Some of these are breaking internal waves, double diffusive instabilities, and sources of random forcing such as surface winds. Satellite photographs of sea surface temperature and atmospheric cloud patterns show that a form of two-dimensional turbulence exists in the atmosphere and ocean. This suggests a cascade of temperature variance from large to small scales due to two-dimensional turbulent mixing. Possibly the final stage of mixing occurs in regions of strong horizontal mean temperature gradients, or fronts, where three-dimensional turbulence formation is enhanced. If the alternate sources of dissipation, particularly internal wave breaking, also concentrate at the fronts, then stratified dissipation may approach log normality.

If each scale of two-dimensional turbulent mixing is independent of each larger and smaller scale of the cascade, the random variable

$$X(r) = \chi(r)/\chi(2r), \quad L > r > L_K \tag{1}$$

should be statistically independent of X(r'>2r) and X(r'< r/2), where  $\chi(r)$  is the average over a horizontal scale r, L the largest scale of the two-dimensional turbulence,  $L_K$  the viscous scale  $(\nu^3/\epsilon)^{1/4}$ , and  $L>r'>L_K$ . If  $L\gg L_K$  then we may compose the identity

$$\chi(r) = \frac{\chi(r)}{\chi(2r)} \frac{\chi(2r)}{\chi(4r)} \cdot \cdot \cdot \frac{\chi(kr)}{\chi(L)} \chi(L)$$
$$= \chi(r) \chi(2r) \cdot \cdot \cdot \chi(kr) \chi(L) \tag{2}$$

Taking the logarithm of Eq. (2) gives

$$l_{n\chi}(r) = l_{n\chi}(r) + l_{n\chi}(2r) + \cdots + l_{n\chi}(kr) + l_{n\chi}(L)$$
 (3)

Since from Eq. (3) the random variable in  $\chi(r)$  is the sum of many independent random variables  $\ell_n X$ , then according to the central limit theorem,  $\ell_n \chi(r)$  should be normally distributed. The expected value in  $\ell_n \chi(r)$  is the sum of expected values of the other random variables in Eq. (3), but  $E(\ell_n X) = 0$  so  $E[\ell_n \chi(r)] = E[\ell_n \chi(L)]$ . The variance of  $\ell_n \chi(r)$  is the sum of the variances of the  $\ell_n X$  variables. If the  $\ell_n X$  variables all have variance  $\sigma_{\ell_n X}^2$  then  $\ell_n \chi(r)$  should have variance  $k \sigma_{\ell_n X}^2$ , where  $k = \log_2(L/L_K)$ .

Log-normal random variables are generally very intermittent, with mode values near zero and much less than the mean or median values. As an example, suppose at some depth in the ocean horizontal temperature regions of scale 100 km (the width of the Cromwell Current is 200 km, and has large meanders) are mixed by two-dimensional turbulence down to a diffusive scale of about 10 cm. Then,  $L/L_K = 10^6$ ,  $\log_2 10^6 = k = 20$ , and from Eq. (3)  $\ln \chi(10 \text{ cm})$  will be Gaussian with mean  $\mu$  and variance  $\sigma^2 = 20\sigma_{la.X}^2$ . The mode of a lognormal random variable is  $\exp(\mu - \sigma^2)$  and the mean is  $\exp(\mu + \sigma/2)$ , so the ratio mean/mode =  $\exp[(3/2)\sigma^2]$ . Assuming (rather arbitrarily, to compare with the data of Figs. 2-4)  $\sigma_{lax}^2 = 0.2$  gives  $\sigma^2 = 4$  for our example with mean exp 6 = 403 times larger than the mode. The median of  $\chi$  is exp  $\mu$ , so the (mean/median) ratio is exp  $\sigma^2/2 = 7.38$ . Therefore half of the  $\epsilon$  samples will be at least a factor of 7 less than the mean  $E(\chi)$ . The probability density function of  $\chi$  is  $(1/\chi\sqrt{2\pi\sigma})$  $\exp\left[-(\ln\chi - \mu)^2/2\sigma^2\right]$  so the probability density of the mean is  $\exp(-9\sigma^2/8) \approx 1/90$  times that of the mode.

In attempting to estimate the mean  $\chi$  at any depth it is important to know whether  $\chi$  is patchy, and whether the patchiness varies with depth. Thus, if  $\chi$  is log normal and  $\mu$ and  $\sigma$  do not vary with depth, a single vertical profile can be used as a large number of representative samples of  $\chi$  if the layer thickness is small compared to the profile depth. However,  $\mu$  and  $\sigma$  generally will vary considerably with depth, since each layer depends on different sources of variance with different time and space scales. For example,  $\mu$  and  $\sigma$  for the shear layers above and below the core of the equatorial undercurrent are probably quite different from each other and from  $\mu$  and  $\sigma$  for the core. Thus if  $\sigma$  varies with depth, the ratio of (mean/mode) =  $\exp(3\sigma^2/2)$  will vary with depth. The observation that the sample values of  $\chi$  and  $\epsilon$  in the core region are less than sample values in the sheared layers may only indicate that  $\sigma_{\rm core} > \sigma_{\rm shear}$ , rather than that  $(\chi, \epsilon)_{\rm core} < (\chi, \epsilon)_{\rm sheared}$ . In fact, if  $\sigma$  is large in all layers, then it is possible that  $(\chi, \epsilon)_{\text{dropsonde}} < (\chi, \epsilon)_{\text{mean}}$  simply because  $(\chi, \epsilon)_{\text{dropsonde}} \approx (\chi, \epsilon)_{\text{mode}} < (\chi, \epsilon)_{\text{mean}}$  when  $\sigma$  is large. This may provide an explanation for the fact that dropsonde estimates of vertical diffusivities from dissipation measurements have been much less than those estimated from mean quantities in the same regions.

Horizontal profiling of dissipation rates have provided little information about  $\mu$  and  $\sigma$  because noise levels have been higher than  $(\chi,\epsilon)_{\text{mode}}$ .  $\chi_{\text{mode}} < 10^{-8} \,^{\circ}\text{C}^2/\text{s}$  and  $\epsilon_{\text{mode}} < 10^{-5} \,^{\circ}\text{cm}^2/\text{s}^3$  in most ocean regions, judging from the dropsonde

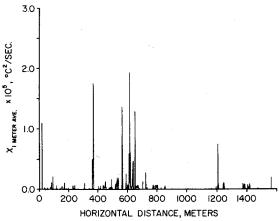


Fig. 2 Temperature dissipation rate  $\chi$  measured from a towed body in the layer of maximum stratification (0.3°C/m) at 36-m depth (Sept. 7, 1977, 50°N 145°W, MILE mixed-layer experiment). The most probable value (mode) of  $\chi$  is less than  $10^{-7}$ °C²/s. A few active microstructure patches dominate the mean value  $\bar{\chi}=0.7\times10^{-6}$ °C²/s. The patches are all fossil temperature turbulence, with  $A_T$  values less than 1.0, shown as triangles in Fig. 5.

measurements, compared to about  $(10^{-7} \,^{\circ}\text{C}^2/\text{s}, 10^{-3} \,^{\circ}\text{cm}^2/\text{s}^3)$  towed body  $(\chi, \epsilon)$  noise levels. To estimate the probability density function of a random variable from a histogram, the noise must be less than the mode or the peak of the pdf will not be resolved. Another difficulty is that the extremely large values of  $\chi$  and  $\epsilon$  in the dominant patches may require frequency response, dynamic range, and spatial resolution beyond the capabilities of the sensors and electronics, so even if such patches are encountered, their contributions may be attenuated.

Figure 2 shows a recent horizontal profile of  $\chi$  estimated from a microconductivity probe on a towed body in the thermocline taken during the 1977 MILE mixed-layer experiment at ocean station P (50°N, 145°W). 25 Simultaneous microbead thermistor signals show that the conductivity signal is dominated by temperature at frequencies up to 25 Hz, and the shape of the diffusive roll-off of the microconductivity signal spectrum suggests that the salinity contribution to conductivity gradients is negligible from frequencies less than 200 Hz. The conductivity probe was mounted on a streamlined body with a large wing and a tether-pulley arrangement to resist vertical motions and also reduce vibrational forces transmitted from the tow cable to the tow body. Vertical excursions of the towed body about the mean depth of 36 m were usually only 10-30 cm at the surface wave period with maximum deviation of less than a meter over several kilometers.

 $\chi$  values were calculated from spectra computed for 1-m records, over a spatial frequency bandwidth of 2-130 cpm. As shown in Fig. 2, the 1-m averaged  $\chi$  values vary over a wide range, from a noise level of about  $10^{-7}\,^{\circ}\text{C}^2/\text{s}$  to peak values over  $10^{-5}\,^{\circ}\text{C}^2/\text{s}$ .  $\bar{\chi}$  for the total record is about  $10^{-6}\,^{\circ}\text{C}^2/\text{s}$ . Most of  $\bar{\chi}$  is due to a small fraction of the total record. The most active 1-m records are not randomly distributed, but tend to cluster together. Most of the 1-m records with  $\chi$  less than  $\bar{\chi}$  are dominated by noise, which means they have  $\chi$  less than  $10^{-7}\,^{\circ}\text{C}^2/\text{s}$ .

Figure 3 shows a comparison of  $\chi$  with log normality for the data of Fig. 2. Average  $\chi$  values for 1-m data records were computed with and without correction for noise. The noise correction was accomplished by subtracting the spectrum from quieter regions from the record spectrum and setting high wavenumber variance to zero above the first point of spectral overlap. Two noise corrected probability distributions are shown corresponding to spectra from two different quieter regions. By this criterion  $\chi$  for about half of the data records was set to zero for one of the correction spectra, as shown by the horizontal portion of the upper

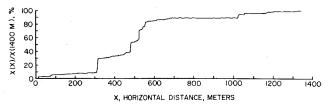


Fig. 3 Log-normality test of  $\chi$  averaged over 1-m records, with and without noise correction. Same data as Fig. 2.

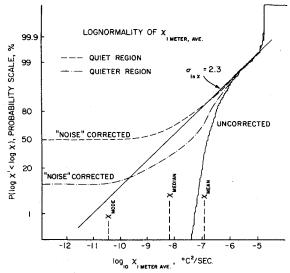


Fig. 4 Accumulated percent temperature gradient variance, expressed as  $\chi(X)/\chi(1400\ m)$ , vs horizontal distance X. Same data as Figs. 2 and 3.

"noise corrected" probability curve in Fig. 3. The lower noise corrected probability curve is an upper bound for the true probability and the uncorrected curve is a lower bound. For the range  $10^{-5} \cdot 10^{-6} \, ^{\circ} \, ^{\circ}$ 

It is clear from Figs. 2 and 3 that  $\chi$  is very patchy in the 36-m depth layer, located below the mixing layer in the strongest temperature gradient portion of the seasonal thermocline. Most of the temperature gradient variance of the record is contained in a few isolated patches. Figure 4 shows accumulated variance as a function of horizontal distance for the data of Fig. 2. Increases occur in sharp steps corresponding to the patches. Eight patches, each with length 5-10 m and  $\chi = 10^{-4} - 10^{-6} \, ^{\circ} \, \text{C}^2/\text{s}$ , give over 80% of the record mean; the rest of the record is close to or below the instrument noise level. A small data sample from either a towed body or dropsonde at this depth will tend to underestimate the space average  $\chi$  by a large factor, of order 10. At least 100 m of record must be averaged for  $\bar{\chi}$  to converge within a factor of 2.

Whether the 1.4 km record shown in Fig. 2 will be adequate to determine the space average  $\chi$  (at 36-m depth) for the 25-km MILE array (or whether the MILE array adequately characterizes the North Pacific Gyre) has not been determined.

#### IV. Fossil Turbulence and Intermittency

Even if the sampling problems of obtaining a mean value of dissipation rates in a spatially patchy layer are overcome, if the turbulence for the layer is intermittent in time the spatial average may not be representative of the space-time average. Temperature profiles in the upper layers often show that the mixed layer deepens quite rapidly rather than by gradual erosion. <sup>22</sup> Enhanced internal wave propagation may transmit intermittent surface forcing much deeper than mixed layer depths. Ozmidov <sup>31</sup> has observed substantial differences in turbulence levels and temperature profile structure at depths of a kilometer before and after a major storm in the Atlantic Ocean.

As indicated in Sec. I, Gibson<sup>7</sup> has shown that most detected oceanic microstructure should be classified as fossil turbulence in an advanced state of decay. Because the original active turbulence patches are missing, the data sets have undersampled the turbulence process and space averages will underestimate the space-time averages. Increasing the time period covered by the microstructure sample may be a practical impossibility. However, it may be possible to make some estimates of the space-time averages from the measured space averages using information about the degree of previous turbulence activity preserved by the fossil turbulence.

The hydrodynamic state of oceanic temperature microstructure is determined using a turbulence activity parameter  $A_T$  introduced by Gibson.  $A_T$  is defined as the ratio  $\gamma_B/\gamma_0'$ , where  $\gamma_B$  is the rate of strain inferred from the diffusive cutoff wavenumber  $k_p$ ,  $\gamma_B = D(k_p/0.3)^2$ ,  $\gamma_0'$  a measure of the rate of strain inferred from the Cox number  $C = (\nabla T)^2 / \nabla T)^2$  assuming the microstructure is actively turbulent,  $\gamma'_0 = 3.6(C/P_r)^{1/2} N$ . Figure 5 shows measured values of  $A_T$  for a variety of oceanic microstructure studies as a function of C. If the microstructure were turbulent,  $A_T$ should be greater than or equal to 1.0. As shown in Fig. 5,  $A_T$ is always less than 1.0. Values for the patches in Fig. 2 are shown as triangles in Fig. 5. Ratios of present to previous values  $\epsilon/\epsilon_0$ ,  $C/C_0$ , and  $\chi/\chi_0$  depend on  $A_T$  as shown in Fig. 5 according to the fossil turbulence model of Gibson, 7,23 where 0 subscripts indicate the values when the turbulence was active with the largest vertical motions of the turbulence barely buoyancy (turbulence at the point of affected by fossilization).

At this time little is known of the persistence time of fossil turbulence, although some estimates can be made. The persistence should increase with increasing  $\gamma_0/N$ . From  $A_T$  or from the overturning scales  $L_T$  of the patch<sup>23</sup> it is possible to estimate  $C_0$ . According to the fossil turbulence model of Gibson,  $^{7}$  C should decrease from  $C_{\theta}$  to  $C_{\theta}(N/\gamma_{\theta})^{\frac{1}{2}}$  in about a Väisälä period  $2\pi N^{-1}$ , and decrease by factors of  $[1-(N/\gamma_0)^{\frac{1}{1}}]$  in each Väisälä period thereafter. Thus from the measured C value and the inferred  $C_{\theta}$  one can infer the number of Väisälä periods the patch has been in existence. The age of a microstructure patch is therefore of order  $(2\pi N^{-1})\ln[C/C_0(N/\gamma_0)^{\frac{1}{2}}]/\ln[1-(N/\gamma_0)^{\frac{1}{2}}]$ . Gibson<sup>23</sup> has used overturning scales measured by Gregg<sup>24</sup> and an expression  $C_0 \approx 0.21 L_T^2 N/D$  to infer  $C_0$  values from microstructure patches in the central North Pacific. The largest patch had overturning scales of 7.5 m, giving a  $C_0$ value of 420,000 compared to the measured value of C = 8. It can be shown <sup>23</sup> that  $\gamma_0/N \approx 1.7 L_T \sqrt{N/\nu}$ , so for the 7.5-m patch  $\gamma_0/N \approx 800$ . Hence, the estimated age for the patch is about 600 Väisälä periods, or 9 days. The time average C for the patch over this period based on the total available temperature variance is of order 100, much larger than C at the time of observation. It should be emphasized that this estimate of fossil age is quite tentative, and is intended to illustrate the sort of calculational procedures that may permit retrieval of information about previous mixing activity perserved by fossil turbulence microstructure.

Although order-of-magnitude best estimates of the corrections for intermittency can be made using models of

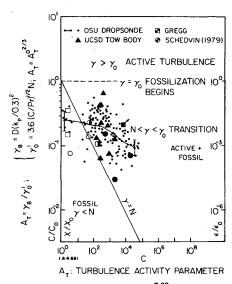


Fig. 5 Turbulence activity parameter  $A_T^{7,28}$  vs Cox number derived from various oceanic temperature microstructure data sets; points and line are from Oregon State dropsonde during MILE  $^{26,27}$ ; triangles are from the active patches of Fig. 2; Schedvin's data  $^6$  are circles; Gregg's data  $^{13,14,24}$  are shown as squares. Open squares and circles indicate vertically stratified microstructure, partially open points are locally isotropic but anisotropic at large scales.

fossil turbulence, as in the preceding example, very little is known about the actual decay laws of fossil turbulence from experiment. From the example it appears that time intermittency corrections may be one or two orders of magnitude. Combined with one or two orders-of-magnitude corrections for undersampling errors due to spatial patchiness, the factor relating the most probable local C value in a layer to the space-time average is 2-4 orders of magnitude. This factor is quite comparable to the discrepancy between dropsonde and towed-body estimates in the core layers of equatorial undercurrents and may provide an explanation; that is, that the towed-body data records are long enough to contain some of the rare patches of mixing activity that dominate the average. Similarly, the large discrepancy between classical eddy diffusivities in the ocean of order 3-90 cm<sup>2</sup>/s, these large values ascribed by Sverdrup et al. 15 others to turbulent mixing, and the much lower values 4,11,24 implied by dropsonde microstructure measurement of dissipation rates may be explained as a possible result of large dropsonde undersampling errors. A satisfactory resolution of the various questions concerning the role of turbulence in mixing and diffusion in the ocean will require larger data sets in space and time, sensor resolution to the viscous and scalar diffusive scales, and much better understanding of the fluid mechanics of stratified turbulence.

### V. Summary and Conclusions

Buoyancy has strong effects on turbulence in stratified fluids such as the ocean and atmosphere. Estimates of vertical flux rate and mixing rates from local measurements of dissipation rate tend to underestimate the actual space-time average because of the spatial patchiness and time intermittency of the turbulence.

As shown in Sec. III,  $\chi$  and  $\epsilon$  conceivably may be described by log-normal probability laws if the primary source of turbulence and mixing is large scale two-dimensional turbulence. Very large differences between the mean and mode values of  $\chi$  can exist. Since a small sample record from a layer will probably give an average near the mode, knowledge of  $\sigma_{\ell\alpha\chi}^2$  for the layer is necessary to estimate the correction factor exp  $(3\sigma_{\ell\alpha\chi}^2/2)$  assuming log normality. Towed-body and submersible measurements of  $\bar{\chi}$  and  $\bar{\epsilon}$  will probably require

correction for spatial patchiness in many ocean regions, and dropsonde measurements will require corrections almost everywhere. The discrepancy between diffusion coefficients in the ocean estimated from dropsonde measurements of dissipation rates and the much larger diffusion coefficients estimated from either mean properties or towed-body dissipation rates may be explained as the result of undersampling of the patchy dissipation by the dropsondes.

Even less is known of the effects of time intermittency on estimates of space-time averages in stratified turbulence, except that intermittency exists and also probably will cause short time averages over space to underestimate the actual space-time average. An attempt was made to show how parameters of fossil turbulence might be used to convert instantaneous values of C to the time average over the life of the fossil patch.

In summary, it appears that oceanic measurements of local dissipation rates by vertical profilers (dropsondes) probably underestimate the space-time average of most layers by about 2-4 orders of magnitude. Corrections for patchiness and intermittency such as those described in this paper would seem to be mandatory if this sampling technique is used. However, the probability laws of stratified turbulence and the decay rates of fossil turbulence which are required in such correction schemes are poorly understood at this time. Horizontal profiling in each layer will give a much larger sample size, but the data processing requirements are enormous. The optimum sampling technique may require a combination of horizontal and vertical profiling plus a much better knowledge of the probability laws and fluid mechanics of stratified turbulence.

#### Acknowledgments

Support for this work was provided by NSF ENG 27398. The data for Figs. 2-4 were collected by John Schedvin and the analysis and plotting was done by Libe Washburn.

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